

## Technical data sheet

### 361C-024-20-S2

#### Continuous control of Spring return actuator

##### Description

**Spring-return Actuator for adjusting and regulating dampers and valves in air conditioning and ventilation.**

- Torque Motor            20 Nm
- Torque Spring        20 Nm
- Nominal Voltage    24 VAC/DC
- Control                Continuous 0(2)...10 VDC
- Auxiliary switch    2 x freely adjustable
- Damper size         up to approx 4 m<sup>2</sup>
- Damper shaft        Clamp  
                               $\diamond$  9-18 mm /  $\varnothing$  9-26 mm



##### Technical data

|                        |  |   |
|------------------------|--|---|
| <b>Electrical data</b> | Nominal voltage                          | 24 VAC (50/60 Hz), 24 VDC   |
|                        | Nominal voltage range                    | 19...29 VAC/DC  |
|                        | Power consumption motor (motion)         | 8,0 W   |
|                        | Power consumption standby (end position) | 2,0 W   |
|                        | Wire sizing                              | 10,0 VA   |
|                        | Control                                  | Continuous<br>0(2)...10 VDC / Ri > 100 k $\Omega$<br>0(4)...20 mA / Rext. = 500 $\Omega$  |
|                        | Position feedback                        | 0(2)...10VDC, max. 5 mA   |
|                        | Auxiliary switch                         | 2 x SPDT (Ag)   |
|                        | Contact load                             | 5 (2,5) A, 250 VAC  |
|                        | Switching point                          | 0°...95°  |
|                        | Connection Motor                         | Cable 1000 mm,<br>4 x 0,75 mm <sup>2</sup> (halogen free)   |
|                        | Connection Auxiliary switch              | Cable 1000 mm,<br>6 x 0,75 mm <sup>2</sup> (halogen free)   |
|                        | Connection GUAC                          | -   |
| <b>Functional data</b> | Torque Motor                             | >20 Nm  |
|                        | Torque Spring                            | >20 Nm  |
|                        | Synchronised speed                       | $\pm$ 5%  |
|                        | Direction of rotation                    | selected by mounting  |
|                        | Manual override                          | Manual operation  |
|                        | Angle of rotation                        | 0°...max.+95°<br>Can be limited with adjustable<br>mechanical end stop min 35°<br>Adaption of operating range<br>to match the mechanical angle of rotation. |
|                        | Running time Motor                       | <150 s / 90°  |

## Technical data

|                           |                                      |  |
|---------------------------|--------------------------------------|--|
| <b>Functional data</b>    | Running time Spring                  | <20 s / 90°  |
|                           | Sound power level Motor              | <35 dB(A)  |
|                           | Sound power level Spring             | <65 dB(A)  |
|                           | Damper coupling                      | Clamp<br>Ø 9...18 mm / Ø 9...26 mm                                     |
|                           | Position indication                  | mechanical with pointer  |
|                           | Service life                         | >60'000 cycles (0° - 95° - 0°)<br>>1'000'000 partial cycles (max. ±5°) |
| <b>Safety</b>             | Protection class                     | III (safety extra-low voltage)   |
|                           | Degree of protection                 | IP54   |
|                           | EMC                                  | CE (2004/108/EG)   |
|                           | LVD                                  | CE (2006/95/EG)  |
|                           | RoHS                                 | CE (2011/65/EU)  |
|                           | Mode of operation                    | Typ 1.AA B (EN60730-1)   |
|                           | Rated impulse voltage                | 0,8 kV (EN60730-1)   |
|                           | Control pollution degree             | 3 (EN60730-1)  |
|                           | Ambient temperature normal operation | -30°C...+50°C  |
|                           | Storage temperature                  | -30°C...+80°C  |
|                           | Ambient humidity                     | 5...95% relative humidity,<br>non condensing (EN 60730-1)              |
|                           | Maintenance                          | maintenance-free   |
| <b>Dimensions/ Weight</b> | Dimensions                           | 193 x 96 x 70 mm   |
|                           | Weight                               | ca. 2.400g   |

## Operating mode / Properties

### Operating mode

Applying the power supply to BU+BN (1+2) and a reference signal Y to BK (3) of 0(2)...10VDC, moves the actuator to position 1. The actual damper position 0...100% is a feedback signal U for example to share the signal with other actuators. If the power supply is interrupted the damper is moving back to the position 0 by spring force. In the position 0, the actuator still provides the rated torque.

The actuator is overload-proof, requires no limit switches and stops automatically when the end position is reached.

### Signaling

The two integrated auxiliary switches are freely adjustable in the angle of 0 – 95°. They are activated corresponding to the adjusted angle. The damper position can be checked by the mechanical pointer.

### Direct mounting

Simple direct mounting on the damper spindle with a universal spindle clamp, supplied with an anti-rotation strap to prevent the actuator from rotating.

### Manual operation

The actuator can be operated manually while the power supply is disconnected. With the supplied lever the position of the damper can be varied and locked. Applying the voltage automatically unlocks the damper.

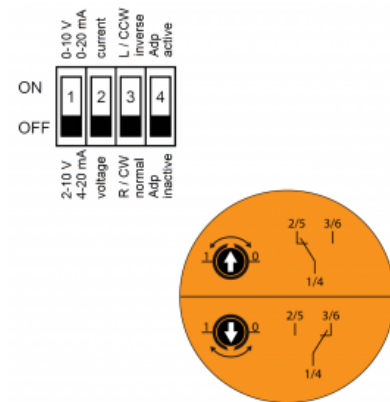
### Mode- switch

DIP-Switch under the case cover

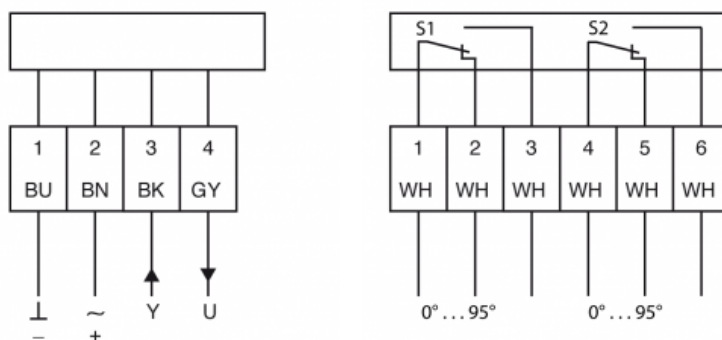
### Adaption drive

Adaptation on angular range < 90°

- Disconnect the power supply
- Set the mechanical end stops
- Connect the actuator to the power supply
- Put DIP-Switch 4 to "ON"
- The actuator is adapting on the angular range
- Put DIP-Switch 4 to "Off"
- “Y” and “U” signals now refer to the adapted angular range



## Connection / Safety remarks



### Safety remarks

- Connect via safety isolation transformer
- The actuator is not allowed to be used outside the specified field of application, especially in airplanes.
- It may only be installed by suitably trained personnel. Any legal regulations or regulations issued by authorities must be observed during assembly.
- The device may only be opened at the manufacturer's site.
- When calculating the required torque, the specifications supplied by the damper manufacturers (cross- section, design, installation site), and the air flow conditions must be observed.
- The actuator is not allowed to be disposed of as household refuse. All locally valid regulations and requirements must be observed.

## Technical drawing

